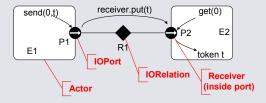


# Examples of Actor-Oriented Component Frameworks

- Simulink (The MathWorks)
- Labview (National Instruments)
- Modelica (Linkoping)
- OCP, open control platform (Boeing)
- GME, actor-oriented meta-modeling (Vanderbilt)
- Easy5 (Boeing)
- SPW, signal processing worksystem (Cadence)
- System studio (Synopsys)
- · ROOM, real-time object-oriented modeling (Rational)
- Port-based objects (U of Maryland)
- I/O automata (MIT)
- VHDL, Verilog, SystemC (Various)
- Polis & Metropolis (UC Berkeley)
- Ptolemy & Ptolemy II (UC Berkeley)
- ٠..

# Actor View of Producer/Consumer Components

## **Basic Transport:**



Many actor-oriented frameworks assume a producer/consumer metaphor for component interaction.

#### Models of Computation:

- push/pull
- continuous-time
- dataflow
- rendezvous
- discrete events
- synchronous
- time-driven
- publish/subscribe
- •...

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### Actor Orientation vs. Object Orientation

- · Object Orientation
  - procedural interfaces
  - a class is a type (static structure)
  - type checking for composition
  - separation of interface from implementation
  - subtyping
  - polymorphism

#### Actor Orientation

- concurrent interfaces
- a behavior is a type
- type checking for composition of behaviors
- separation of behavioral interface from implementation
- behavioral subtyping
- behavioral polymorphism 🔷



Focus on this

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This is a vision of the future: Few actor-oriented frameworks

fully offer this view.

Eventually, all will.

## Polymorphism

- Data polymorphism:
  - Add numbers (int, float, double, Complex)
  - Add string (concatenation)
  - Add composite types (arrays, records, matrices)
  - Add user-defined types

#### Behavioral polymorphism:

- In dataflow, add when all connected inputs have data
- In a time-triggered model, add when the clock ticks
- In discrete-event, add when any connected input has data, and add in zero time
- In process networks, execute an infinite loop in a thread that blocks when reading empty inputs
- In CSP, execute an infinite loop that performs rendezvous on input or output
- In push/pull, ports are push or pull (declared or inferred) and behave accordingly
- In real-time CORBA, priorities are associated with ports and a dispatcher determines when to add



By not choosing among these when defining the component, we get a huge increment in component reusability. But how do we ensure that the component will work in all these circumstances?

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# Object-Oriented Approach to Achieving Behavioral Polymorphism

#### «Interface» Receiver

+get(): Token

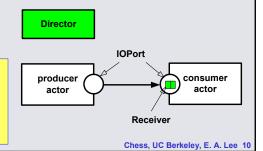
+getContainer() : IOPort +hasRoom() : boolean +hasToken() : boolean

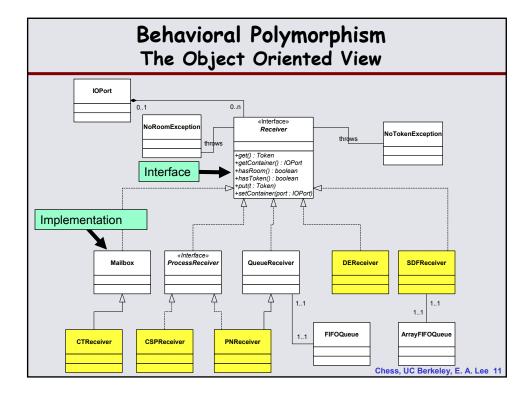
+put(t: Token)

+setContainer(port : IOPort)

These polymorphic methods implement the communication semantics of a domain in Ptolemy II. The receiver instance used in communication is supplied by the director, not by the component.

# Recall: Behavioral polymorphism is the idea that components can be defined to operate with multiple models of computation and multiple middleware frameworks.





## But What If...

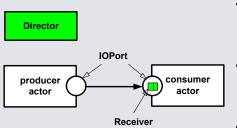
- The component requires data at all connected input ports?
- The component can only perform meaningful operations on 2 successive inputs?
- The component can produce meaningful output before the input is known (enabling it to break potential deadlocks)?
- The component has a mutex monitor with another component (e.g. to access a common hardware resource)?

None of these is expressed in the object-oriented interface definition, yet each can interfere with behavioral polymorphism.



# Behavioral Types - A Practical Approach

- Capture the dynamic interaction of components in types
- Obtain benefits analogous to data typing.
- Call the result behavioral types.



See Liskov & Wing, ACM, 1994 for an intro to behavioral types.

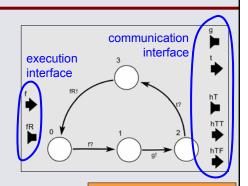
- Communication has
  - data types
  - behavioral types
- Components have
  - data type signatures
  - behavioral type signatures
- · Components are
  - data polymorphic
  - behaviorally polymorphic

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# Behavioral Type System

- We capture patterns of component interaction in a type system framework.
- We describe interaction types and component behavior using extended interface automata (de Alfaro & Henzinger)
- We do type checking through automata composition (detect component incompatibilities)
- Subtyping order is given by the alternating simulation relation, supporting behavioral polymorphism.

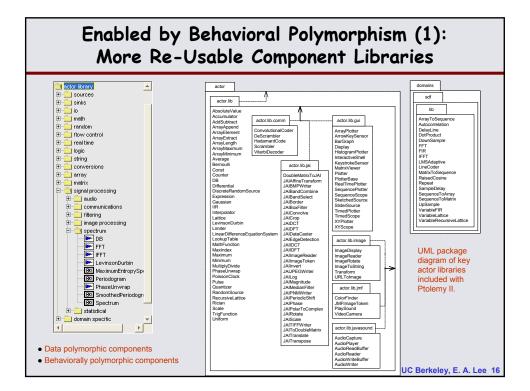
These behavioral types are an example of an *interface theory* (Henzinger, et al).

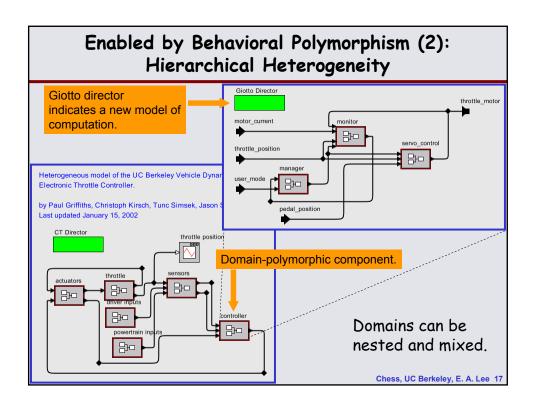


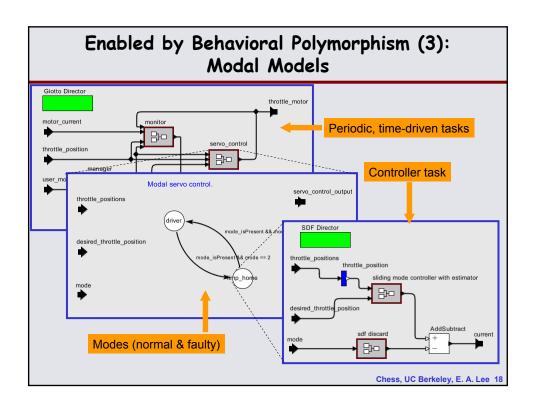
A type signature for a consumer actor.

## Enabled by a Behavioral Type System

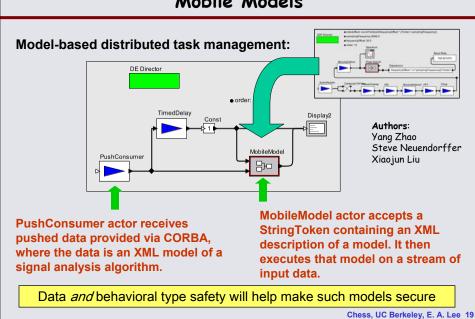
- Checking behavioral compatibility of components that are composed.
- Checking behavioral compatibility of components and their frameworks.
- Behavioral subclassing enables interface/implementation separation.
- Helps with the definition of behaviorallypolymorphic components.







# Enabled by Behavioral Polymorphism (4): Mobile Models



## Conclusion - What to Remember

- Actor-oriented design
  - concurrent components interacting via ports
- Models of computation
  - principles of component interaction
- Behavioral types
  - a practical approach to verification and interface definition
- Behavioral polymorphism
  - defining components for use in multiple contexts

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