

TEAM OF GEEKS

- **Zhiyuan Guo (Architect)**

- Compiler, Code generation, Semantics

- **Guitang Lan (Language Guru)**

- Compiler, Semantic validation, Test case creation

- **Jin Liang (Tester)**

- Test case creation, Testing automation, Documentation

- **Chenzhe Qian (Manager)**

- Python libraries, Code generation, Documentation



INTRODUCTION

- Is Vector same as Matrix?
- What is Vector Space?
- Why on earth need Matrix?



Why not MATLAB?



How about Python and others?

- Set vector EQUALS matrix
- Mixed math concepts with data structures

GOAL

Math education

Linear algebra programming



**Solve X with real math language
in computer!**

$$Ax=B$$

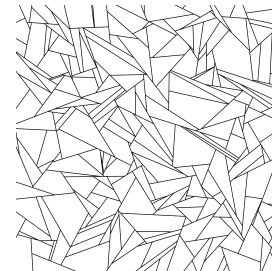
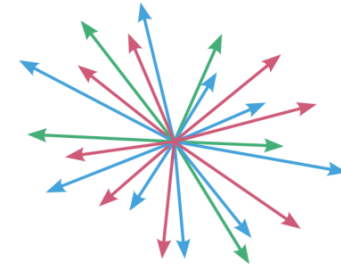
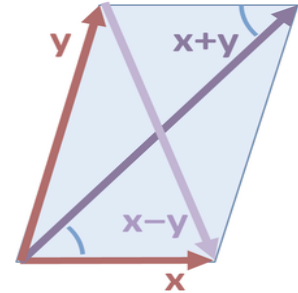
TYPES

Featured Primitive Types

- **vector**
- **matrix**
- **vecspace**
- **inspace**
- **affspace**

Common Primitive Type

- **var**



DECLARATIONS

var a = 1.2

vector b = [1,2]

matrix c = [1,2;2,8;]

vecsapce d = L([1,2],[3,4])

inspace e = inspace({[1,0],[0,1]}, c)

affspace f = affspace(b, d)

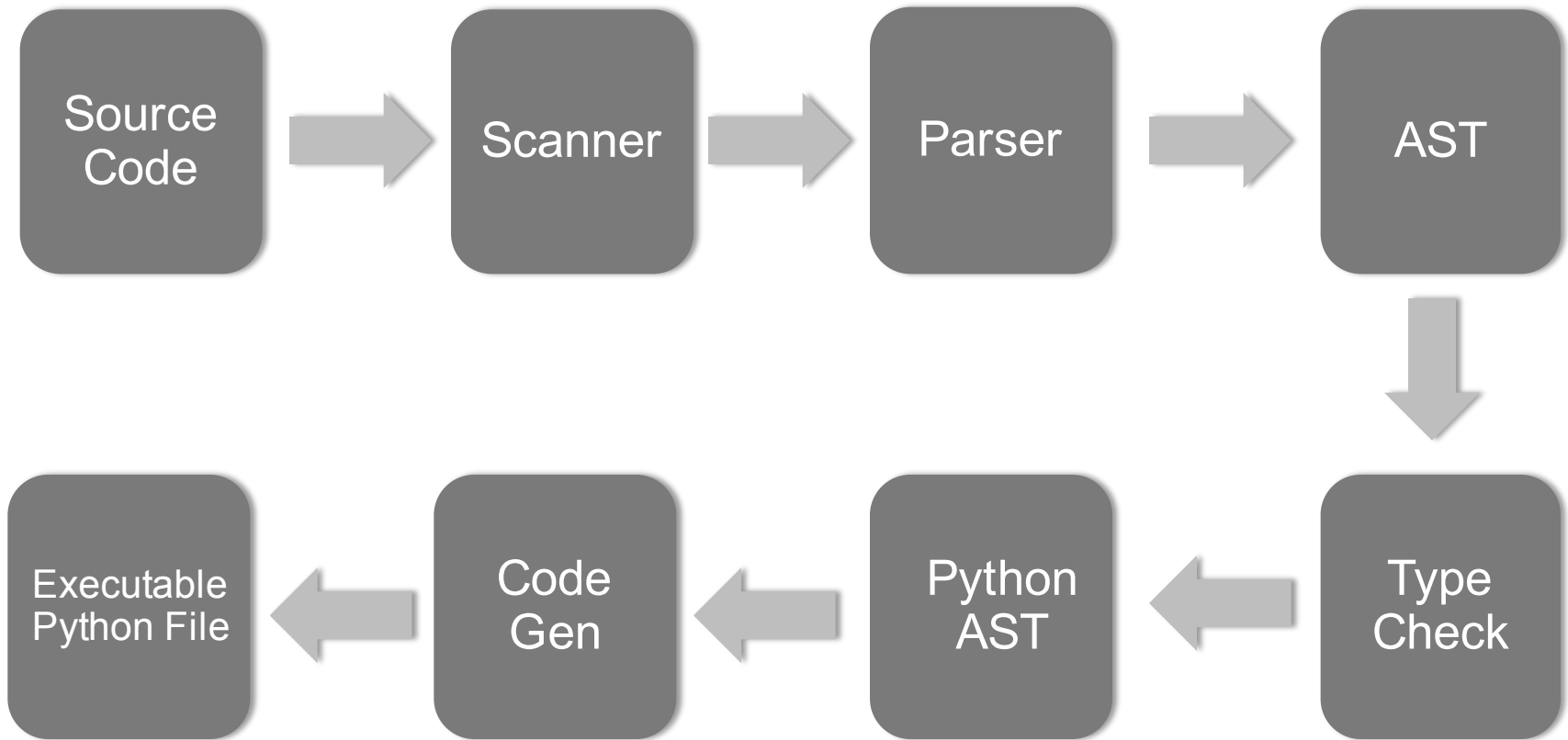
FEATURED OPERATORS

- **Belongs @:**
 - $\text{vector@vecspace (affspace)}$
- **LieBracket [[,]]**
 - $[[\text{matrix}, \text{matrix}]]$
- **Innerproduct << , >>**
 - $\text{id}<<\text{vector}, \text{vector}>>$
- **Matrix action &**
 - $\text{matrix} \& \text{vector}$

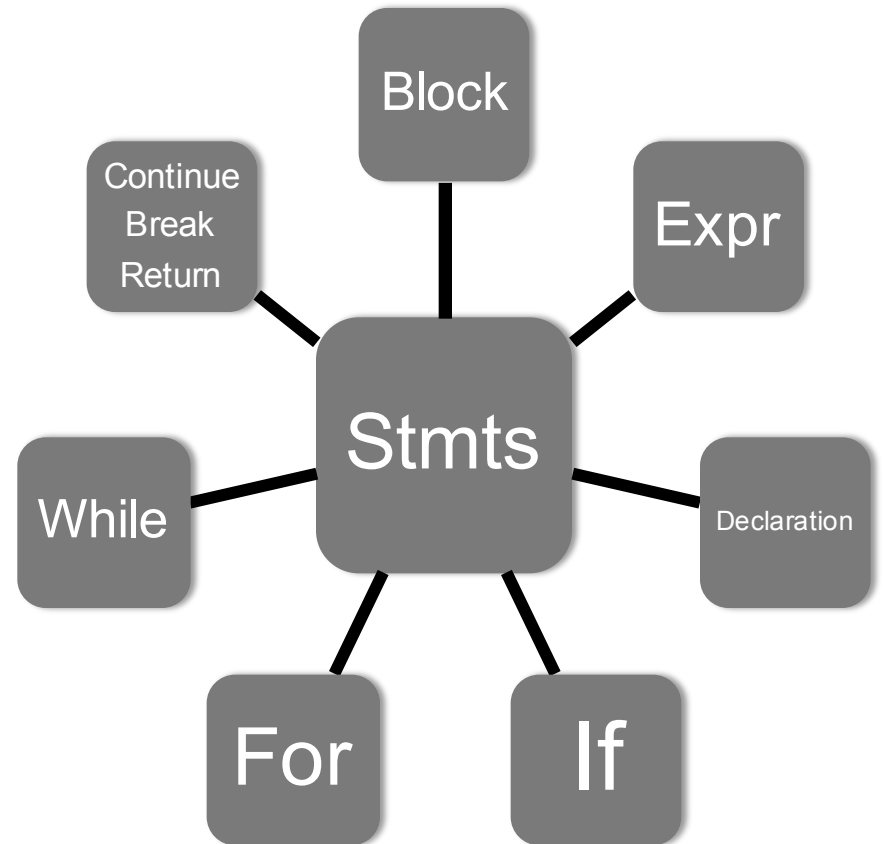
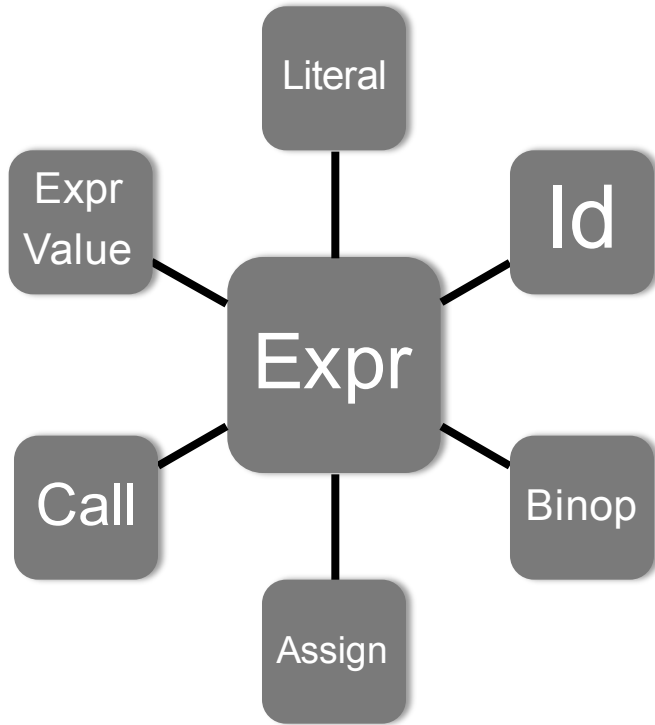
FEATURED BUILT-IN FUNCTION

- **dim(argument)**
 - argument is vector, vecspace, inspace or affspace
- **basis(vecspace)**
 - return a basis of the vecspace
- **solve(matrix, vector)**
 - return an affspace
 - the solution set of linear equation $m * x = v$

ARCHITECTURE



AST



TRANSLATION ENVIRONMENT

- **Scope: symbol_table**
- **Functions: func StringMap.t**
- **Global_Variables: var StringMap.t**
- **In_While: bool**
- **In_For: bool**

symbol_table:

- **Parent : symbol_table**
- **Vars : var StringMap.t**

SCOPE RULE

- **Global Variable**
 - from defined to end
- **Function Parameters**
 - inside function
- **Local variables**
 - valid inside the nearest block

```
1 var i = 4;
2
3 function foo(var a)
4 {
5     if a > 2
6     {
7         var b = a+2;
8         print(b);
9     }
10    else
11    {
12        var c = 2;
13        if a > 0
14        {
15            c = c+2;
16        }
17        print(c);
18    }
19
20    print(i);
21 }
22
23
24 function main()
25 {
26     foo(1);
27 }
```

TYPE CHECK

- **Data Type**
 - Variable declaration and assign
 - Array declaration and element assign
 - Function parameters pass
- **Function return type**
 - Our function definition doesn't declare function return type explicitly, so compiler check return type.
- **Control flow**
 - Conditional expression type check

CODE GEN

```
1 #!/usr/bin/python
2 import sys
3 sys.path.append('./lib')
4 from InSpace import *
5 from AffSpace import *
6 from Core import *
7
8 def othonormalising(bases, ips, n) :
9     vec=np.array([])
10    bases[0] = bases[0] / sqrt(ips.product(bases[0],bases[0]))
11    i=0
12    for i in range(1, n) :
13        vec = bases[i]
14        j=0
15        for j in range(0, i) :
16            vec = vec - ips.product(bases[i],bases[j]) * bases[j]
17
18        bases[i] = vec / sqrt(ips.product(vec,vec))
19
20    return bases
21
22 def main() :
23     n=2
24     v1=np.array([1,2,3])
25     v2=np.array([2.3,2,4])
26     bases=[v1,v2]
27     v4=np.array([1,0,0])
28     v5=np.array([0,1,0])
29     v6=np.array([0,0,1])
30     mat=np.matrix(((1,0,0),(0,1,0),(0,0,1)))
31     vecs=[v4,v5,v6]
32     ins=InSpace(vecs,mat)
33     print(othormalising(bases, ins, n))
34
35 main()
```

TESTING

- **Test Suites**
- **Testing Cases**
- **Automation Testing**
- **Test Roles**



AUTOMATION TESTING

- **Fast feedback to the team**
- **Free up time**
- **A sense of confidence**
- **An automated script**



test_affspace_construction_and_belong.la
test_affspace_construction_and_belong.out
test_affspace_dim.la
test_affspace_dim.out
test_arithmetic_typecheck.la
test_arithmetic_typecheck.out
test_arithmetic.la
test_arithmetic.out
test_array_assign.la
test_array_assign.out
test_array_assign2.la
test_array_assign2.out
test_array_index.la
test_array_index2.la
test_array_index2.out
test_array_print.la
test_array_print.out
test_assignment_array.la
test_assignment2.la
test_assignment2.out
test_block_scope.la
test_block_scope.out
test_break_statement.la
test_break_statement.out
test_builtin_ceil.la
test_builtin_ceil.out
test_builtin_floor.la
test_builtin_floor.out
test_builtin_sqrt.la
test_builtin_sqrt.out
test_comment.la
test_comment.out
test_for_loop.la
test_for_loop.out
test_function_arguments.la
test_function_arguments1.la
test_function_arguments1.out

test_function_arguments.la
test_function_arguments1.la
test_function_arguments1.out
test_function_arguments2.la
test_function_arguments2.out
test_function_local.la
test_function_local.out
test_if_statement.la
test_if_statement.out
test_if_typecheck.la
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test_inspace_construction.out
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test_invalid_syntax.la
test_LieBracket.la
test_LieBracket.out
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test_matrix_divide_dot.la
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test_matrix_multiple_dot_two_matrix.la
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test_matrix_plus_dot.la
test_matrix_plus_dot.out
test_matrix_print.la

test_matrix_size.la
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test_matrix_substraction.la
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test_sample2.la
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test_while_loop.out
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test_arith4.la
test_arith4.out
test_arith5.la
test_arith5.out
test_arith6.la
test_arith6.out
test_arith7.la
test_arith7.out
test_arith8.la
test_arith8.out
test_arith9.la
test_arith9.out
test_arith10.la
test_arith10.out
test_arith11.la
test_arith11.out
test_var1.la
test_var1.out

EXAMPLES

```
1 function linearIndep(vector[] vectors, var n)
2 {
3     if n==1 { return 1; }
4     if n > dim(vectors[0])
5         { return 0; }
6
7     vecspace vs;
8     var i;
9     for i = 0:n
10    {
11        if vectors[i]@vs
12            {return 0;}
13        vs = vs + L(vectors[i]);
14    }
15
16    return 1;
17 }
18
19 function main()
20 {
21     vector v = [1,2,3];
22     vector u = [2,22,3];
23     vector w = v + u;
24     vector x[2] = { v, u};
25     vector y[3] = {v, u, w};
26
27     print(linearIndep(x, 2));
28
29     print(linearIndep(y, 3));
30 }
```

```
1 function othonormalising (vector[] bases, inspace ips, var n)
2 {
3     vector vec;
4
5     bases[0] = bases[0] /.(sqrt(ips<<bases[0],bases[0]>>));
6
7     var i;
8     for i = 1:n
9     {
10        vec = bases[i];
11        var j;
12        for j= 0:i
13            {
14                vec = vec - ips<<bases[i], bases[j]>>*.bases[j];
15            }
16        bases[i]=vec/.(sqrt(ips<<vec, vec>>));
17    }
18    return bases;
19 }
20
21 function main()
22 {
23     var n = 2;
24     vector v1 = [1,2,3];
25     vector v2 = [2.3, 2, 4];
26
27
28     vector bases[2] = {v1,v2};
29
30     vector v4 = [1,0,0];
31     vector v5 = [0,1,0];
32     vector v6 = [0,0,1];
33
34     matrix mat = [1,0,0;0,1,0;0,0,1];
35     vector vecs[3] = {v4, v5, v6};
36     inspace ins = inspace(vecs, mat);
37
38     print(othonomalising(bases,ins, n));
39 }
```

HOW WE WORKED

OCaml 59.0%

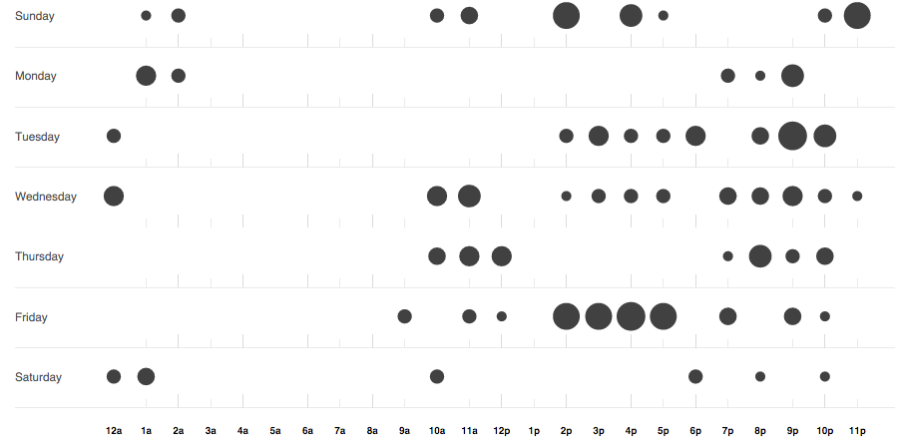
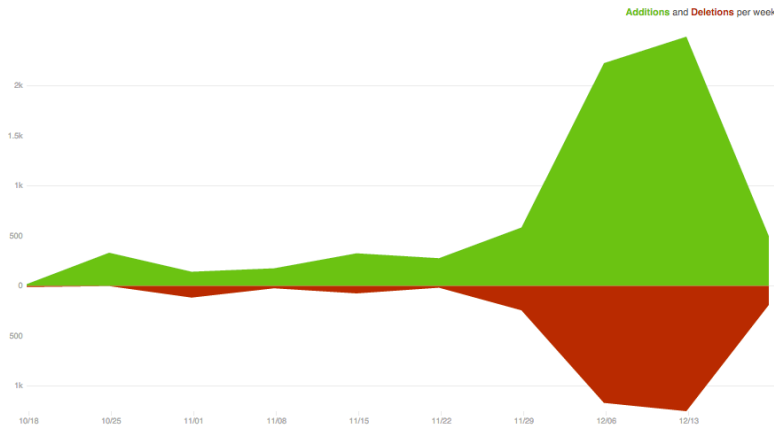
TeX 28.7%

Python 6.4%

Standard ML 2.6%

Shell 2.2%

Makefile 1.1%



30 Active Issues

28
Closed Issues

2
New Issues



LESSONS LEARNED

- **Start EARLY**
- **Meet regularly**
- **Plan ahead**
- **Communication**
- **Collaboration is key! (Github, Google Drive, WeChat)**

DEMO



THANK YOU