



Facelab: A Portrait Photos Editing Language

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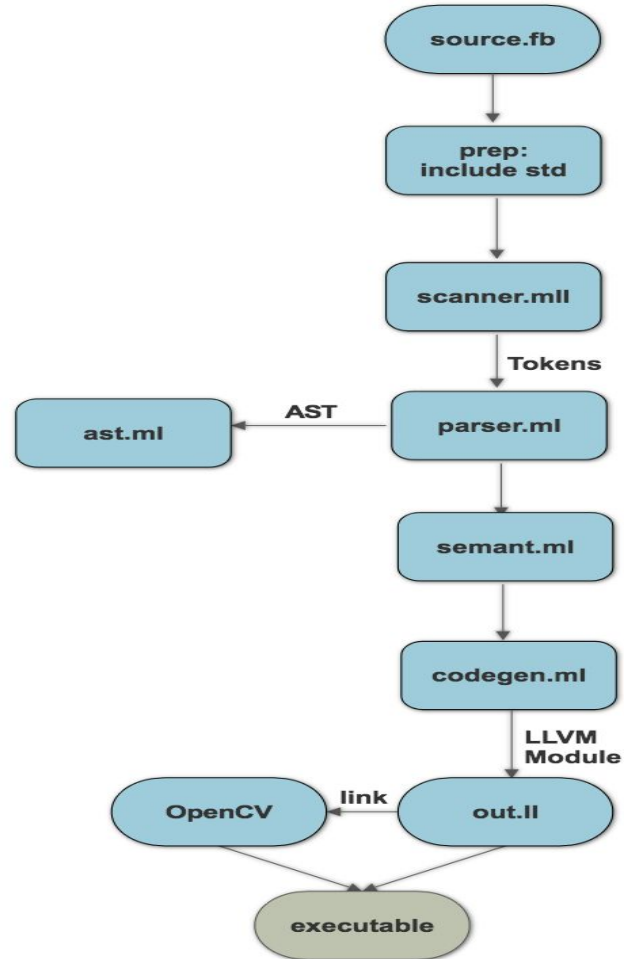
Introduction

01 face detection, filter, photo sticker

02 hybrid of C and Matlab syntax

03 have OpenCV linked

Architecture





Data types

Type	Description
int	32-bit signed integer
double	64-bit float-point number
bool	1-bit boolean variable
string	array of ASCII characters
matrix	data structure storing bool/ints/doubles of arbitrary size



Keywords -- reserved by the language

- **Compound statement:** for, while, if, elseif, else.
- **Control flows:** return.
- **Boolean values:** true, false.
- **Function declaration:** func
- **Data types:** int, double, bool, string, matrix



Matrix literals

A sequence of digits enclosed by a pair of square brackets, and delimited by commas and semi-colons, representing an un-named 2-D matrix.

$$\text{e.g. } [1.1, 2.2; 3.3, 4.4] = \begin{bmatrix} 1.1 & 2.2 \\ 3.3 & 4.4 \end{bmatrix}$$



Basic Operators

<code>=, +, -, *, /, %</code>	Arithmetic operations
<code>!=, ==, <, >, <=, >=</code>	Comparison
<code> , &&, !</code>	Logic operators
<code>.*</code>	Matrix dot product
<code>M[i, j]</code>	Access matrix entry at (i, j)
<code>M[i, :]</code>	Subscribe i-th row
<code>M[:, j]</code>	Subscribe j-th column
<code>\$</code>	Operator to add filter to a matrix



Function declaration & Scoping

- ❖ function declaration can be interleaved with statements and expressions.
- ❖ both function name and variable name follow static scoping rule.

```
func f1() { return; } //void type
f1();
f2(); // error msg(Semantic error : f2 not defined.)
func f2() { return 5;} //int type
f2()
```




Return type inference

- ❖ `func f1() { return; } //void type`
- ❖ `func f2(int i, int j) { return i*j; } // int type`
- ❖ `func f3(double d) { return d+3.3; } //double type`
- ❖ `func f4(string s) { return s; } // string type`
- ❖ `func f5(int i, int j) { return i==j; } // bool type`
- ❖ `func f6(matrix m, matrix n) { return m.*n; } //matrix type`



Return type inference

- ❖ HOWTO: Search for return statement in each function, and determine the type of return expression.

- ❖ Trick for implementing recursive function call:

```
func factorial (int i)
{
    if (i != 1) { return i * factorial (i-1); }
    else { return 1; }
}
```



Return multiple values

- ❖ Since we do not provide reference operator, return multiple seems necessary.

```
func rot90(double x, double y)
{
    return -y, x;
}
double x; double y;
x, y = rot90(x, y);
```



Return multiple values

```
func rot90(double x, double y)
{
    return -y, x;
}
double x; double y;
x, y = rot90(x, y);
```

- ❖ Store all return data in a struct at llvm level, then assign to each variable one by one.



Matrix indexing

- ❖ `m[:, :]` //returns the whole matrix.
- ❖ `m[:x_high, :]` //returns row 0 to row x_high.
- ❖ `m[x_low:, :]` //returns row x_low to last row.
- ❖ `m[x_low:x_high, :]` //returns row x_low to x_high
- ❖ `m[x, y] = m[x:x, y:y]` //returns the entry at(x, y) (double)



Matrix assignment

- ❖ matrix assignment

```
m1 = m2; // their sizes do not have to agree.
```

- ❖ block assignment

```
m1[x_low:x_high, y_low:y_high] = m2; // their size must agree.  
(so m[:,:] is different from m in assignment)
```



OpenCV related built-in function

- ❖ `m_r, m_g, m_b = load(path)`
 - store image in RGB order
- ❖ `save(m_r, m_g, m_b, path)`
 - save image defined by RGB matrices
- ❖ `m = face(path)`
 - use OpenCV cascade classifier
 - `m` is a 4 by `n` matrix
 - `n`: # of faces; row 1: x-coordinates of the center of faces; row 2: y-coordinates of the center of faces; row 3: height of the faces; row 4: width of faces.

(all above function are interface in Facelab to functions from open CV.)



Other built-in function

- ❖ `size`
 - `i, j = size(m)`
 - `m: matrix; i: row; j: column`
- ❖ `zeros`
 - `m = zeros(i, j)`
- ❖ `double2int`
 - `d = double2int(i)`
- ❖ `int2double`
 - `d = int2double(i)`



Std.fb

Built-in functions such as `filter` is loaded at compile stage.

Filter

5*5 or 3*3 image kernels can be easily applied to rgb matrix using built in filter function \$.

\$ is left-associative so multiple kernels can be applied at the same time.

Matrix result = origin \$ filter1 \$ filter2 \$...





Thank you!

Demo