**EECS 20. Final Exam. December 21, 2004.** Use these sheets for your answer and your work. Use the backs if necessary. Write clearly and put a box around your answer, and show your work.

Print your name and lab day and time below

Name: \_\_\_\_\_

Lab day and time:

Problem 1:

Problem 2:

Problem 3:

Problem 4:

Problem 5:

Problem 6:

Total:

- 1. 15 points, 3 points each part Give precise definitions of the following:
  - (a) The space *Images* of all  $600 \times 900$  images with pixel values in  $\{0, 1, \dots, 255\}$ .

(b) A one-to-one and onto function  $f:[0,\infty) \to [0,1)$ .

- (c) A linear one-to-one function  $f: Complex \rightarrow Reals^2$ .
- (d) The spaces *ContSignals* and *DiscSignals* of continuous-time and discrete-time complex-valued signals (use the [ ] notation):

Now define the system

 $Sampler_T : ContSignals \rightarrow DiscSignals$ which samples its input every T sec.

(e) The convolution z = x \* y when i.  $x, y : Reals \rightarrow Reals$ .

ii. x, y: Ints  $\rightarrow$  Reals.

- 2. 15 points Design two state machines, both with  $Inputs = \{0, 1\}$ ,  $Outputs = \{0, 1, 2\}$ , and with input-output functions  $S_1, S_2$  given below.
  - (a) 7 points

 $\forall x, \forall n \quad S_1(x)(n) = (n_1 - n_0) \bmod 3,$ 

in which  $n_1$  and  $n_0$  are the numbers of 1's and 0's in  $(x(0), \dots, x(n))$ , respectively.

## (b) 8 points

$$\forall x, \forall n \quad S_2(x)(n) = \begin{cases} 0, & \text{if } (n_1 - n_0) \text{ is even} \\ 1, & \text{if } (n_1 - n_0) \text{ is odd} \end{cases}$$

in which  $n_1, n_0$  are as above.

3. 15 points, 5 points each part Consider a LTI system with [A, b, c, d] representation given by:

$$A = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}, \quad b = \begin{bmatrix} 0 \\ 1 \end{bmatrix}, \quad c^T = \begin{bmatrix} 1 & 0 \end{bmatrix}, \quad d = 0.$$

(a) Calculate the zero-input state response when the initial state is  $s(0) = [s_1(0) \quad s_2(0)]^T$ .

(b) Calculate the (zero-state) impulse response, h.

(c) Calculate the response  $y(n), n \ge 0$  when the initial state is  $s(0) = \begin{bmatrix} 1 & 1 \end{bmatrix}^T$  and the input signal is  $\forall n \ge 0, x(n) = \delta(n-1)$ .

4. 20 points Consider the difference equation

$$y(n) - 2y(n-1) = x(n) - 3x(n-1).$$

(a) **4 points** Take the state at time n as  $s(n) = [y(n-1), x(n-1)]^T$  and write down the [A, b, c, d] representation of the system.

(b) **4 points** Implement the difference equation using two delay elements whose outputs are the two state components.

(c) **6 points** Find another implementation using only *one* delay element and find the [A, b, c, d] representation for this implementation.

(d) **6 points** Determine the zero-state impulse response.

- 5. **15 points** The bandwidth of a continuous time signal x with FT X is by definition the smallest frequency  $\omega_B$  such that  $X(\omega) = 0$  for  $|\omega| > \omega_B$ .
  - (a) **3 points** What is the bandwidth of the signals:  $\forall t \in Reals$ ,

 $x_k(t) = \sin(10k\pi t), k = 1, 2, 3; \quad x_4(t) = x_1(t) + x_2(t) + x_3(t).$ 

Specify the units of the bandwidth.

(b) **3 points** What is the FT of  $x_k, k = 1, \dots, 4$ ?

(c) **4 points** Suppose  $x_k$  is sampled at frequency  $\omega_s = 30\pi$  rad/sec. Find a simple expression for the sampled signal  $y_k$ .

(d) **5 points** Find signals  $z_k : Reals \to Reals$  such that (i) the bandwidth of  $z_k$  is smaller than  $15\pi$  rad/sec, which is one-half the sampling frequency; and (ii) if  $z_k$  is sampled at frequency  $\omega_s$  it also yields the signal  $y_k$ .

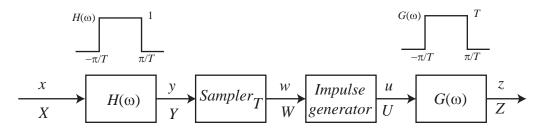


Figure 1: Setup for problem 6

- 6. 20 points, 5 points each part Consider the setup of figure 1. The filters H, G are as shown; the sampling period is T seconds.
  - (a) Express w, u in terms of y and W, U in terms of Y.

- (b) Express Z in terms of X.
- (c) Determine y and z for T = 0.1s and  $\forall t, x(t) = \sin(25\pi t) + \sin(5\pi t)$ .
- (d) Suppose in this setup H is changed to  $\forall \omega, H(\omega) = 1$ . Take T, x as above, and determine z.

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