EECS 20. Midterm No. 2 April 16, 2002.

Please use these sheets for your answer and your work. Use the backs if necessary. Write clearly and put a box around your answer, and show your work.

Print your name and lab TA's name below

Name:		
Lab TA:		
Problem 1:		
Problem 2:		
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Total:		

1. **30 points.** Consider a continuous-time signal $x : Reals \rightarrow Reals$ defined by

 $\forall t \in Reals, \ x(t) = 3 + 2\sin(3t) + 3\cos(4t).$

(a) Obtain the Fourier series coefficients of x(t), i.e., find the coefficients A_0, A_1, A_2, \ldots and ϕ_1, ϕ_2, \ldots and w_0 such that

$$x(t) = A_0 + \sum_{k=1}^{\infty} A_k \cos(kw_0 t + \phi_k).$$

(b) Obtain the Fourier series expansion for x(t), i.e., find the coefficients X_k for all $k \in Integers$ such that

$$x(t) = \sum_{k=-\infty}^{\infty} X_k e^{ikw_0 t} \quad .$$

(c) Consider a continuous-time LTI system $Filter : [Reals \rightarrow Reals] \rightarrow [Reals \rightarrow Reals]$ with the following frequency response:

$$H(w) = 2, |w| \ge 2,$$

 $H(w) = 0, |w| < 2.$

Such a filter is an amplifying high-pass filter. Give a simple expression for the output y(t) of the system, where y = Filter(x).

2. 20 points. Consider a system whose input and output are related by

 $\forall n \in Integers, \ y(n) = 2 \ x(n-2) + 1.1 \ y(n-1).$

(a) Construct a state-space model for the system. It is sufficient to give the state definition, the A matrix, vectors b and c, and scalar d.

(b) Give an expression for the zero-state impulse response.

(c) Recall that a system is stable if a bounded input always produces a bounded output. Is this system stable? Explain.

25 points. Consider discrete-time systems with input x : Integers → Reals and output y : Integers → Reals. Each of the following defines such a system. For each of the following, indicate whether it is linear only (L), time-invariant only (TI), both (LTI), or neither (N). Note that no partial credit will be given for these questions.

(a)
$$\forall n \in Integers, y(n) = x^3(n-10) = (x(n-10))^3$$

- (b) $\forall n \in Integers, y(n) = \cos(x(n))$
- (c) $\forall n \in Integers, y(n) = n$
- (d) $\forall n \in Integers, y(n) = \max\{|x(n)|, |x(n-1)|\}$
- (e) $\forall n \in Integers, y(n) = x(-n)$

4. **15 points.** Consider a continuous-time LTI system S. Suppose that when the input is given by

$$x(t) = \begin{cases} \sin(\pi t) & 0 \le t < 1\\ 0 & \text{otherwise} \end{cases}$$

then the output y = S(x) is given by

$$y(t) = \begin{cases} \sin(\pi t) & 0 \le t < 1\\ \sin(\pi(t-2)) & 2 \le t < 3\\ 0 & \text{otherwise} \end{cases}$$

for all $t \in Reals$.

- (a) Carefully sketch these two signals.
- (b) Give a simple expression and a sketch for the output of the same system if the input is

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$$x(t) = \begin{cases} \sin(\pi t) & 0 \le t < 1 \\ -\sin(\pi(t-1)) & 1 \le t < 2 \\ 0 & \text{otherwise} \end{cases}$$

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